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ON THE INTERCHANGE OF SUBDIFFERENTIATION AND CONDITIONAL EXPECTATION FOR CONVEX FUNCTIONALS

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ABSTRACT

We show that the operators E^{G} (conditional expectation given a τ -field G) and ϑ (subdifferentiation), when applied to a normal convex integrand f, commute if the effective domain multifunction $\omega \rightarrow \{x \in \mathbb{R}^{n} | f(\omega, x) < +\infty\}$ is G-measurable.

ON THE INTERCHANGE OF SUBDIFFERENTIATION AND CONDITIONAL EXPECTATION FOR CONVEX FUNCTIONALS

R.T. Rockafellar and R. J-B. Wets

We deal with interchange of conditional expectation and subdifferentiation in the context of stochastic convex analysis. The purpose is to give a condition that allows the commuting of these two operators when applied to convex integral functionals.

Let (Ω, A, P) be a probability space, G a τ -field contained in A, and f an A-normal convex integrand defined on $\Omega \times R^n$ with values in $R \cup \{\infty\}$. The latter means that the map

$$\omega \rightarrow \text{epi } f(\omega, \cdot) = \{ (\mathbf{x}, \alpha) \in \mathbb{R}^{n+1} | \alpha \geq f(\omega, \mathbf{x}) \}$$

is a closed-convex-valued A-measurable multifunction. See [2] and [9] for more on normal integrands and their properties. In particular recall that for any A-measurable function $x: \Omega \rightarrow R^n$, the function

$$\omega \rightarrow \mathbf{f}\left(\omega, \mathbf{x}\left(\omega\right)\right)$$

is a A-measurable and the *integral functional* associated with f is defined by

$$I_{f}(x) = \int f(\omega, x(\omega)) P(d\omega)$$

To bypass some trivialities we impose the following summability conditions:

(1) there exists a *G*-measurable $x: \Omega \to \mathbb{R}^n$ such that $I_f(x)$ is finite, (2) there exists $v \in L_n^1(G) = L^1(\Omega, G, P; \mathbb{R}^n)$ such that $I_{f*}(v)$ is finite, where f^* is the (A-normal) conjugate convex integrand, i.e.

$$f^{*}(\omega, \mathbf{x}) = \sup_{\mathbf{x} \in \mathbb{R}^{n}} [\mathbf{v} \cdot \mathbf{x} - f(\omega, \mathbf{x})]$$

Finally, we assume that A -- and hence also G -- is countably generated, and that there exists a *regular* conditional probability (given G), $P^{G}: A \times \Omega \rightarrow [0,1]$. Whenever we refer to the conditional expectation given G, we always mean the version obtained by integrating with respect to P^{G} . Consequently all conditional expectations will be regular.

In particular the conditional expectation $E^{G}f$ of f is the G-normal integrand defined by

$$(\mathbf{E}^{G}\mathbf{f})(\boldsymbol{\omega},\mathbf{x}) = \int f(\boldsymbol{\zeta},\mathbf{x}) \mathbf{P}^{G}(\mathrm{d}\boldsymbol{\zeta} \mid \boldsymbol{\omega})$$

Also given $\Gamma: \Omega \stackrel{\rightarrow}{\rightarrow} \mathbb{R}^n$, a closed-valued A-measurable multifunction, its conditional expectation given G is a closed-valued G-measurable multifunction obtained via a projection-type operation from a set

$$L_{\Gamma}^{1} = \{ u \in L^{1}(\Omega, A, P; \mathbb{R}^{n}) | u(\omega) \in \Gamma(\omega) \text{ a.s.} \} \subset L_{n}^{1}(A)$$

onto $L_n^1(G) = L^1(\Omega, G, P; \mathbb{R}^n)$. Valadier has shown that a regular version $E^G \Gamma: \Omega \stackrel{2}{\rightarrow} \mathbb{R}^n$ is given by the expression

$$\mathbf{E}^{G}\Gamma(\omega) = \mathbf{cl}\left\{\int \mathbf{u}(\zeta) \mathbf{P}^{G}(d\zeta \mid \omega) \mid \mathbf{u} \in L_{n}^{1}(A), \mathbf{u}(\omega) \in \Gamma(\omega) \text{ a.s.}\right\}.$$

We refer to [12] and the references given therein for the properties of $E^{G}f$; in particular to the article of Dynkin and Estigneev [3], which specifically deals with regular conditional expectations of measurable multifunctions.

We consider I_f and $I_{E_{n}}^{G}$ as (integral) functionals on $L_{n}^{\infty}(A)$ and $L_{n}^{\infty}(G)$ respectively. The natural pairings of L^{∞} with L^{1} and $(L^{\infty})^{*}$ yield for each functional two different subgradient multifunctions. We shall use ∂I_{f} and ∂I_{f} for designating L^{1} -subgradients and $\partial^{*}I_{f}$ and $\partial^{*}I_{f}$ for $(L^{\infty})^{*}$ -subgradients. Rockafellar [8, Corollary 1B] shows that when the summability conditions (1) and (2) are satisfied, one has the following representation for $(L^{\infty})^{*}$ -subgradients:

(3)
$$\partial^* I_f(x) = \{v + v_s | v \in \partial I_f(x), v_s \in S_n(A) \text{ with } v_s [x - x'] \ge 0 \forall x' \in \text{dom } I_f \}$$

where $S_n(A)$ is the space of *singular* continuous linear functionals on $L_n^{\infty}(A)$, and

dom
$$I_f = \{x \in L_n^{\infty}(A) \mid I_f(x) < +\infty\}$$

is the effective domain of I_f . (For the decomposition of $(L_n^{\infty})^*$ consult [2, Chapter VIII]). Furthermore the L^1 -subgradient set is given by

(4)
$$\partial I_{f}(\mathbf{x}) = \{ \mathbf{v} \in L_{n}^{1}(A) \mid \mathbf{v}(\omega) \in \partial f(\omega, \mathbf{x}(\omega)) \text{ a.s.} \}$$

The summability conditions (1) and (2) on f imply similar properties for $E^{G}f$, so the formulas above also apply to I. Thus for $x \in L_{n}^{\infty}(G)$ we get

(5)
$$\partial_{E}^{*}I_{G_{f}}(\mathbf{x}) = \{\mathbf{u}+\mathbf{u}_{s} | \mathbf{u} \in \partial I_{E}^{G_{f}}(\mathbf{x}), \mathbf{u}_{s} \in S_{n}^{G_{f}}(G)$$

with $\mathbf{u}_{s}[\mathbf{x}-\mathbf{x'}] \geq 0$, $\forall \mathbf{x'} \in \text{dom } I_{E}^{G_{f}}\}$

and

(6)
$$\exists \mathbf{I}_{E^{G}f}(\mathbf{x}) = \{ \mathbf{u} \in L_{n}^{1}(G) | \mathbf{u}(\omega) \in \exists E^{G}f(\omega, \mathbf{x}(\omega)) \text{ a.s.} \}$$
.

We are interested in the relationship between ∂I_f and $\partial I_E^G f$. Relying on the formulas just given, Castaing and Valadier [2, Theorem VIII.37] show that if in place of the summability conditions (1) and (2), one makes the stronger assumption:

(7) there exists $x^{\circ} \in L_{n}^{\infty}(G)$ at which I_{f} is finite and norm continuous,

then for every $x \in L_n^{\infty}(G)$ one gets:

(8)
$$\partial I_{E^{G_{f}}}(\mathbf{x}) = E^{G}(\partial I_{f}(\mathbf{x})) + rc[\partial I_{E^{G_{f}}}(\mathbf{x})]$$

where rc denotes the recession (or asymptotic) cone [2,7]. If $x \in int \text{ dom I}_{E^{G}f}$, $\partial I_{E^{G}f}(x)$ is weakly compact and then $rc[\partial I_{E^{G}f}(x)] = E^{G}f$ {0}, in which case

(9)
$$\partial I_{E^{G_{f}}}(x) = E^{G} \partial I_{f}(x)$$

This was already observed by Bismut [1, Theorem 4]. For the subspace of L_n^{∞} of constant functions, Hiriart-Urruty [4] obtains a similar result for the ε -subdifferentials of convex functions.

Here we shall go one step further and provide a condition under which the rc term can be dropped from the identity (8) without requiring that $x \in int \text{ dom I}_f$. Very simple examples show that the rc term is sometimes inescapable in (8). For instance, suppose $G = \{\phi, \Omega\}$ (so $E^G = E$) and consider $f(\omega, \cdot) = \psi_{(-\infty, \xi(\omega))}$, the indicator of the unbounded interval $(-\infty, \xi(\omega))$, where ξ is a random variable uniformly distributed on [0,1]. In this case $\psi_{(-\infty,0]} = Ef = E^G f = I_{E^G f}$, so that $\partial I_{E^G f}(0) = R_+$ but $E^G(\partial I_f(0)) = E\{0\} = \{0\}$. Thus (8) would fail without the rc term.

<u>THEOREM</u>. Suppose f is an A-normal convex integrand such that the closure of its effective domain multifunction

(10)
$$\omega \mapsto D(\omega) := cl dom f(\omega, \cdot) = cl \{x \in \mathbb{R}^n | f(\omega, x) < +\infty\}$$

-4-

is G-measurable. Assume that $I_f(x) < +\infty$ for every $x \in L_n^{\infty}(G)$ such that $x(\omega) \in \text{dom } f(\omega, \cdot)$ a.s., and that there exists $x^0 \in L_n^{\infty}(G)$ at which I_f is finite and norm continuous. Then for every $x \in L_n^{\infty}(G)$ one has

(11)
$$\partial \mathbf{E}^{G} \mathbf{f}(\cdot, \mathbf{x}(\cdot)) = \mathbf{E}^{G} \partial \mathbf{f}(\cdot, \mathbf{x}(\cdot)) \text{ a.s. },$$

or in other words, the closed-valued G-measurable multifunctions

$$\omega \mapsto \partial \mathbf{E}^{G} \mathbf{f} (\omega, \mathbf{x} (\omega))$$

and

$$\boldsymbol{\omega} \mapsto \mathbf{E}^{G}[\partial \mathbf{f}(\boldsymbol{\cdot}, \mathbf{x}(\boldsymbol{\cdot}))](\boldsymbol{\omega})$$

are almost surely equal.

Proof. From (8) it follows that

$$\operatorname{di}_{\mathbf{E}^{G} \mathbf{f}}(\mathbf{x}) \subset \operatorname{E}^{G}(\operatorname{di}_{\mathbf{f}}(\mathbf{x}))$$

In view of (6) and (4) this holds if and only if

$$\partial \mathbf{E}^{G} \mathbf{f}(\cdot, \mathbf{x}(\cdot)) \subset \mathbf{E}^{G} \partial \mathbf{f}(\cdot, \mathbf{x}(\cdot))$$
 a.s.

It thus suffices to prove the reverse inclusion. Let us suppose that $u \in \partial E^{G}f(\cdot, x(\cdot))$. For every $y \in R^{n}$, define

$$g(\omega, y) = f(\omega, y) - u(\omega) \cdot y$$

This is an A-normal convex integrand which inherits all the properties assumed for f in the Theorem (recall that $u \in L_n^1(G)$). Moreover $0 \in \partial E^G g(\cdot, x(\cdot))$. We shall show that $0 \in E^G \partial g(\cdot, x(\cdot))$, which in turn will imply that $u \in E^G \partial f(\cdot, x(\cdot))$ and thereby complete the proof of the Theorem.

Since almost surely $0 \in \partial E^{G_{g}}(\omega, \mathbf{x}(\omega))$, we know that $0 \in \partial I_{E_{g}}(\mathbf{x}) \subset \partial^{*}I_{E_{g}}(\mathbf{x})$. Hence \mathbf{x} minimizes $I_{E_{g}}$ on $L_{n}^{\infty}(G)$. Let inj denote the natural injection of $L_n^{\infty}(G)$ into $L_n^{\infty}(A)$ with

$$W = inj [L_n^{\infty}(G)]$$

Now note that inj $\overline{\mathbf{x}} = \overline{\mathbf{x}}$ also minimizes I on $\mathcal{W} \subset L_n^{\infty}(A)$, or equi-E^Gg valently I on \mathcal{W} , since the two integral functionals coincide on \mathcal{W} (by the definition of conditional expectation.) Thus

$$0 \in \partial^* (\mathbf{I}_g + \psi_{\mathcal{U}}) (\mathbf{x})$$

where $\psi_{\mathcal{W}}$ is the indicator function of \mathcal{W} , or equivalently:

$$0 \in \partial^* \mathbf{I}_{\mathbf{g}}(\mathbf{x}) + \partial^* \psi_{\mathcal{U}}(\mathbf{x})$$

since g is (norm) continuous at some $x^{\circ} = inj \ x^{\circ} \in W$. By (3), this means that there exist $v \in L_n^1(A)$, $v_s \in S_n(A)$, such that

(12) $v(\omega) \in \partial g(\omega, x(\omega))$ a.s.

(13)
$$v_s[x-x'] \ge 0$$
 for all $x' \in \text{dom } I_q$

and $-(v + v_s)$ is orthogonal to W, i.e.

(14)
$$(v+v_s)[x'] = 0$$
 for all $x' \in W$

This last relation can also be expressed as

$$(v + v_{g})$$
 [inj y] = 0 for all $y \in L_{p}^{\infty}(G)$

or still for all $y \in L_n^{\infty}(G)$

$$\operatorname{inj}^{*}(\mathbf{v} + \mathbf{v}_{s})[\mathbf{y}] = 0$$

where $\operatorname{inj}^*: (L_n^{\infty}(A))^* \to (L_n^{\infty}(G))^*$ is the adjoint of inj. Thus the continuous linear functional $\operatorname{inj}^*(v + v_s)$ must be identically 0 on $L_n^{\infty}(G)$, i.e. on $L_n^{\infty}(G)$ one has

(15)
$$inj^{*}v_{s} = -inj^{*}v = -E^{G}v$$

The last equality follows from the observation that $E^G \approx inj^*$ when inj^{*} is restricted to $L_n^1(A)$, cf. [2, p.265] for example.

We shall complete the proof by showing that the assumptions (12), (13) and (15) imply that

(16)
$$(\mathbf{v} - \mathbf{E}^G \mathbf{v})(\omega) \in \partial g(\omega, \mathbf{x}(\omega))$$
 a.s.

This will certainly do, since it trivially yields the sought-for relation

$$0 = E^{G}(v - E^{G}v) \in E^{G} \exists g(\cdot, x(\cdot))$$

To obtain (16), it will be sufficient to show that

(17)
$$E\{(-E^{G}v)(\omega) \cdot [x(\omega) - y(\omega)]\} \ge 0$$

for all $y \in \text{dom } I_g \subseteq L_n^{\infty}(A)$. To see this, recall that the relations (17) and $v \in \partial I_g(x)$ (cf. (12)) imply that $v - E^G v \in \partial I_g(x)$, from which (16) follows via the representation of L^1 -subgradients given by (4). In fact, because the effective domain multifunction, or more precisely its closure $\omega \mapsto D(\omega)$, is G-measurable, it is sufficient to show that (17) holds for every $y \in \text{dom } I_g \cap W$. Suppose to the contrary that (17) holds for every $y \in \text{dom } I_g \cap W$ -or equivalently because of the \leq inequality that (17) holds for every $y \in \text{cl dom } I_g \cap W$ -- but there exists $\hat{y} \in L_n^1(A)$ such that $I_a(\hat{y}) < +\infty$ and for which (17) fails, i.e. we have

$$\mathbf{E}\{(-\mathbf{E}^{G}\mathbf{v})(\omega)\cdot[\mathbf{x}(\omega)-\hat{\mathbf{y}}(\omega)]\} < \mathbf{0}$$

Because $-E^{G}v$ and x are G-measurable, this inequality implies that

(18)
$$\mathbf{E}\{(-\mathbf{E}^{G}\mathbf{v})(\omega)\cdot[\mathbf{x}(\omega) - \mathbf{E}^{G}\hat{\mathbf{y}}(\omega)]\} < 0$$

Moreover, since $I_q(\hat{y}) < +\infty,$ it follows that almost surely

$$\hat{\mathbf{y}}(\boldsymbol{\omega}) \in \operatorname{dom} \mathbf{g}(\boldsymbol{\omega}, \boldsymbol{\cdot}) \subset \mathbf{D}(\boldsymbol{\omega})$$

Taking conditional expectation on both sides, we see that

(19)
$$(\mathbf{E}^{\hat{G}}\hat{\mathbf{y}})(\omega) \in \mathbf{E}^{\hat{G}}\mathbf{D}(\omega) = \mathbf{D}(\omega)$$

because D is a closed-valued G-measurable multifunction. Naturally $E^{\hat{G}}_{\hat{Y}} \in W$. Because I_g is by assumption finite on $\{z \in L_n^{\infty}(G) \mid z(\omega) \in \text{dom } g(\omega, \cdot) \text{ a.s.}\}$, and $D(\omega) = \text{cl dom } g(\omega, \cdot)$, it follows from (19) that $E^{\hat{G}}_{\hat{Y}} \in \text{cl dom } I_g$. Hence (17) cannot hold for every $y \in \text{dom } I_g \cap W$ since $E^{\hat{G}}_{\hat{Y}}$ belongs to (cl dom $I_g \cap W$ and satisfies (18).

There remains only to show that (17) holds for every $y \in L_n^{\infty}(G)$ such that inj $y = y \in \text{dom } I_g$. But now from (13) we have that for each such y

$$v_{g}[x-y] = v_{g}[inj x - inj y] \ge 0$$

or again equivalently: for each $y \in \text{dom } I_{\alpha} \cap L_{n}^{\infty}(G)$,

 $(inj^*v_s)[x-y] \ge 0$.

But this is precisely (17), since we know from (15) that on $L_n^{\infty}(G)$, $\operatorname{inj}^* v_{e} = -E^{G} v$. \Box

<u>COROLLARY</u>. Suppose f is a A-normal convex integrand such that $F(x) < +\infty$ whenever $x \in \text{dom } f(\omega, \cdot)$ a.s., where

 $\mathbf{F}(\mathbf{x}) = \mathbf{E}\{\mathbf{f}(\boldsymbol{\omega}, \mathbf{x})\} \quad .$

Suppose moreover that there exists $x^{\circ} \in \mathbb{R}^{n}$ at which F is finite and continuous, and that the multifunction

$$\omega \mapsto D(\omega) = cl dom f(\omega, \cdot)$$

is almost surely constant. Then for all $\mathbf{x} \in \mathbb{R}^n$,

(20) $E[\partial f(\cdot, \mathbf{x})] = \partial F(\mathbf{x})$,

where the expectation of the closed-valued measurable multi-

function Γ is defined by

$$E\Gamma = cl\{ \int v(\omega) P(d\omega) | v \in L_n^1(A), v(\omega) \in \Gamma(\omega) \text{ a.s.} \}$$

<u>*PROOF*</u>. Just apply the Theorem with $G = \{\phi, \Omega\}$, and identify the class of constant functions -- the *G*-measurable functions -- with \mathbb{R}^{n} . \Box

This Corollary was first derived by Ioffe and Tikhomirov [5] and later generalized by Levin [6]. Note that our definition of the expectation of a closed-valued measurable multifunction is at variance with the definition now in vogue for the integral of a measurable multifunction, which does not involve the closure operation. (Otherwise the definition of the integral of a multifunction would be inconsistent with that of its conditional expectation, in particular with respect to $G = \{\phi, \Omega\}$, and also when $\Gamma \neq E\Gamma$ is viewed as an integral on a space of closed sets it could generate an element that it is not an element of that space.)

APPLICATION

Consider the stochastic optimization problem:

(21) find inf
$$E[f(\omega, x_1(\omega), x_2(\omega))]$$
 over all $x_1 \in L_{n_1}^{\infty}(G)$, $x_2 \in L_{n_2}^{\infty}(A)$,

where A and G are as before, and f is an A-normal convex integrand which satisfies the norm-continuity condition:

(22) there exists
$$(\mathbf{x}_1^\circ, \mathbf{x}_2^\circ) \in L_{n_1}^\infty(G) \times L_{n_2}^\infty(A)$$

at which I_f is finite and norm continuous.

Suppose also that the effective domain multifunction

$$\omega \neq \text{dom } f(\omega, \cdot, \cdot) = \{ (\mathbf{x}_1, \mathbf{x}_2) \in \mathbb{R}^{n_1} \times \mathbb{R}^{n_2} | f(\omega, \mathbf{x}_1, \mathbf{x}_2) < +\infty \}$$

is uniformly bounded and that there exists a summable function $h \in L^{1}(A)$ such that $(x_{1}, x_{2}) \in \text{dom } f(\omega, \cdot \cdot)$ implies that

$$\begin{split} |f(\omega, \mathbf{x}_1, \mathbf{x}_2)| &\leq h(\omega). & \text{Finally suppose that the multifunction} \\ \omega &\mapsto D_1(\omega) &= \text{cl} \{\mathbf{x}_1 \in \mathbb{R}^{n_1} | \exists \mathbf{x}_2 \in \mathbb{R}^{n_2} \text{ such that } f(\omega, \mathbf{x}_1, \mathbf{x}_2) < +\infty \} \end{split}$$

is G-measurable. For a justification and discussion of these assumptions cf. [11, Section 2]. From Theorem 1 of [11], it follows that the problem

(23) find inf
$$E[g(\omega, x_1(\omega))]$$
 over all $x_1 \in L_{n_1}^{\infty}(G)$

where

$$q(\omega, x_1) = E^{G} \{ \inf f(\cdot, x_1, x_2) \}(\omega)$$

$$x_2 \in \mathbb{R}^{n_2}$$

is equivalent to (21) in the sense that if $(\overline{x}_1, \overline{x}_2)$ solves (21), then \overline{x}_1 solves (23), and similarly any solution x_1 of (23) can be "extended" to a solution (x_1, x_2) of (21). Both problems also have the same optimal value.

The hypotheses imply that

$$(\omega, \mathbf{x}_1) \mapsto \inf_{\mathbf{x}_2} f(\omega, \mathbf{x}_1, \mathbf{x}_2)$$

is an A-normal convex integrand, since the multifunction $\omega \mapsto \operatorname{epi}(\inf_{x_2} f(\omega, x_1, x_2))$ is closed-convex-valued and A-measurable. Its effective domain multifunction, or more precisely

$$\omega \mapsto D_1(\omega) := cl dom q(\omega, \cdot)$$

is G-measurable. Combining (11) with the representation for the subgradients of infimal functions [13, VIII.4], we have that for every $x_1 \in L_{n_1}^{\infty}(G)$

$$\partial q(\cdot, \mathbf{x}_{1}(\cdot)) = \mathbf{E}^{G} \{ \mathbf{v}(\omega) \mid (\mathbf{v}(\omega), 0) \in \mathbf{a.s.} \partial f(\omega, \mathbf{x}_{1}(\omega), \mathbf{x}_{2})$$

for some $\mathbf{x}_{2} \in \mathbb{R}^{n_{2}} \} (\cdot)$

from which Theorem 2, the main result of [11], follows directly.

<u>REMARK</u>. If the underlying probability measure P has finite support, then $(L_n^{\infty})^* = L_n^1$, and (11) and (20) are satisfied without any other restriction.

On the other hand, if P is nonatomic, and the effective domain multifunction (or its closure) is not G-measurable, then the identities (11) and (20) do not apply. More precisely, suppose that there exists a subset C of R^n such that the Ameasurable set

$$\{\omega \mid \text{dom } f(\omega, \cdot) \cap C \neq \phi\}$$

has (strictly) positive mass and is not *G*-measurable. Then the term $\operatorname{rc}[\partial I_{E_{f}}(x)]$ can never be dropped from the representation of $\partial I_{E_{f}}$ given by (8), as can be seen from an adaptation of the $E_{f}^{G_{f}}$ arguments in Section 4 of [10]. In those cases the inclusion $E_{f}^{G_{f}} \cap \partial E_{f}^{G_{f}}$ will be strict for at least some $x \in L_{n}^{\infty}(G)$.

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